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(57) Abstract:

The present invention discloses a semi-autonomous object dispensing robot that is user friendly. The robot has been designed to perform the pick and drop tasks of daily needs. It takes the inputs such as time and distance from where the object has to be picked and the inputs of the distance and direction of the final destination. The robot activates itself at the respective time to pick the object from the desired location and then dispense it to the final destination without any error. The robot can be made to be custom programmed with the help of a keypad anytime by the user according to the need and the task that needs to be performed.

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